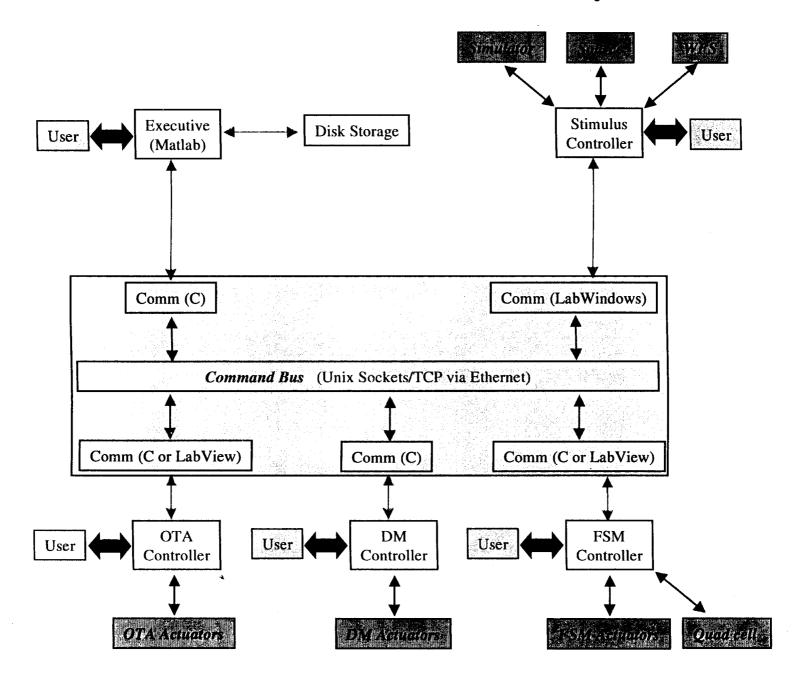
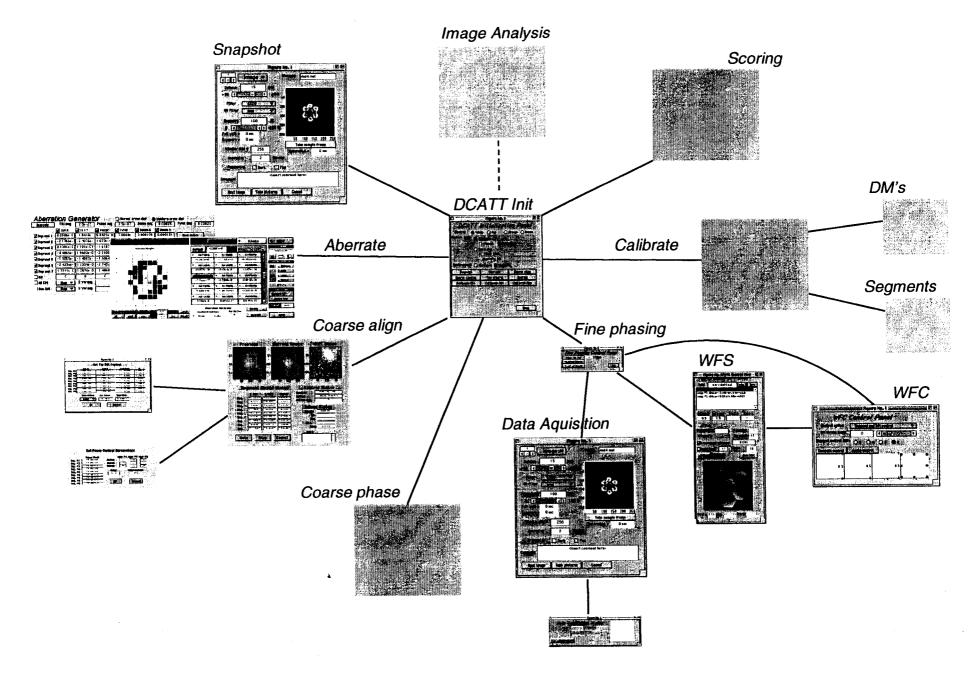
# Controlling the DCATT/NEXCAT Hardware

Scott Basinger, Laura Burns, David Redding Brendon Perkins, Ladd Wheeler, Jennifer Deering

### **DCATT** Architecture Summary

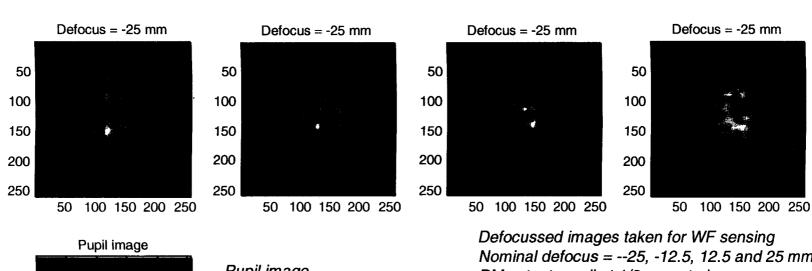


## Executive Overall Flow Diagram





### **Typical Images**



100 200 300 400 500

Pupil image White light source 632.8±1.5nm filter 40 sec exposure

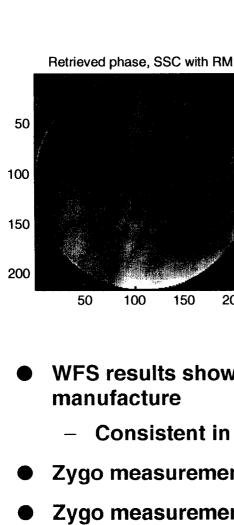
Shows slight offset, taper at edge Truncated gaussian profile Defocussed images taken for WF sensing
Nominal defocus = --25, -12.5, 12.5 and 25 mm
DM actuators all at 1/8 max stroke
Images show stripes due to OAP figure errors,
astigmatism, DM actuator features

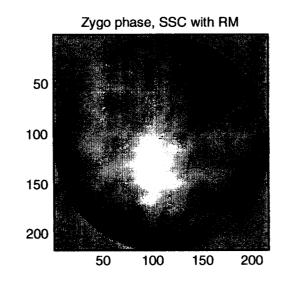
images irom inst data run

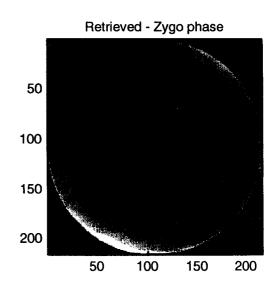


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### WFS and Zygo Measurements: Return Mirror







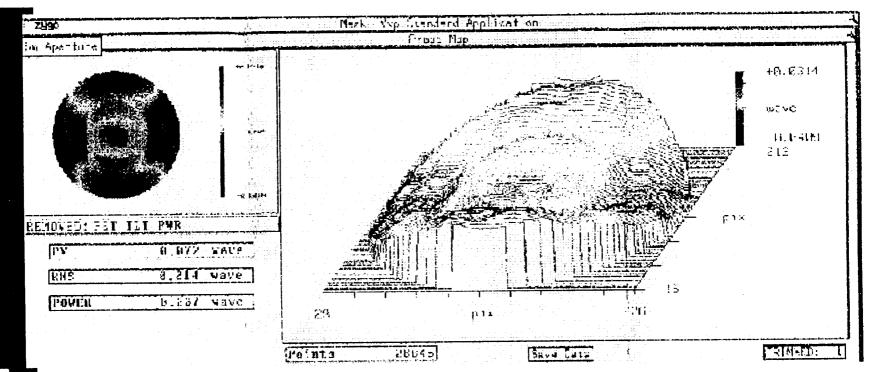
- WFS results show gouges in OAP from figuring and polishing during OAP manufacture
  - Consistent in both measurements, removed in difference frame
- Zygo measurement shows bump, focus, astigmatism missing in WFS results
- Zygo measurements noisy, differences from frame to frame up to 0.1 wave in astigmatism and coma
- WFS results show ring artifacts

200



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## **Zygo Transmission Sphere Surface Map**

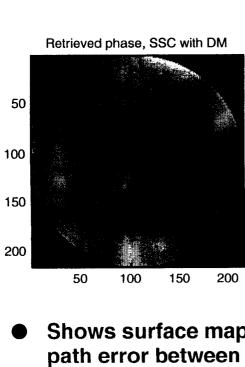


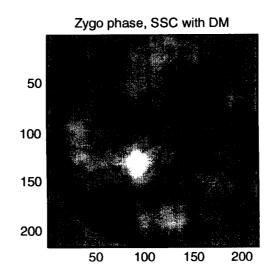
- Shows surface map of Zygo transmission sphere -- part of total noncommon path error between DCATT WFS and Zygo measurements
- Qualitatively consistent with WFS Zygo residuals
  - Magnitude, astigmatic character, dip near center
  - Residuals also include BS non-common path effects

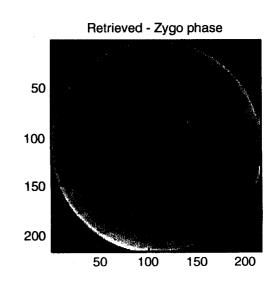


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## WFS and Zygo Measurements: Deformable Mirror



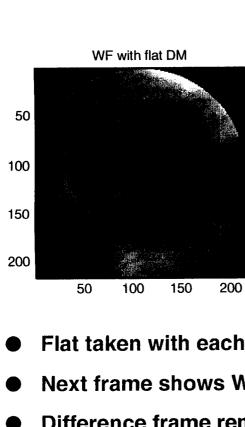


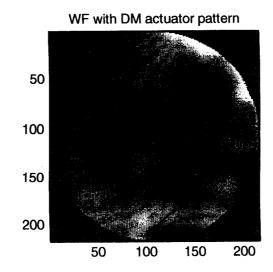


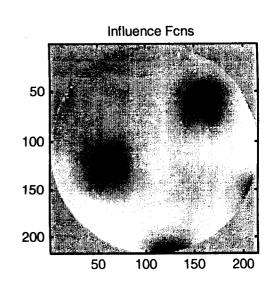
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- Qualitatively consistent with WFS Zygo residuals
  - Magnitude, astigmatic character, dip near center
  - Residuals also include BS non-common path effects



### **DM Calibration**



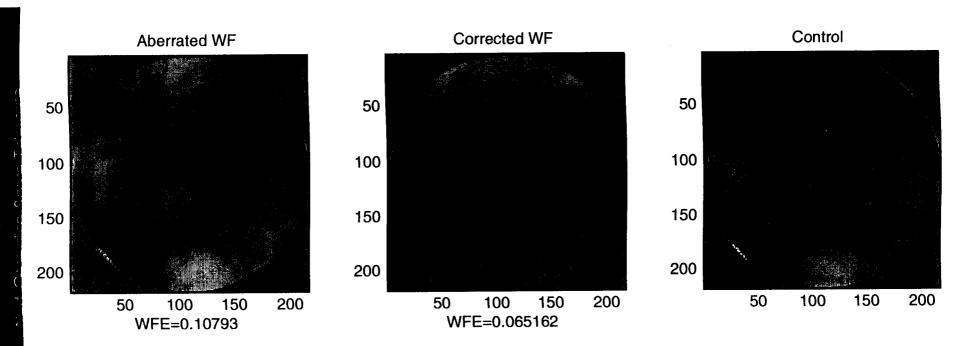




- Flat taken with each DM actuator commanded to 128\*63/4096
- Next frame shows WF after 4 actuators increased to 255\*63/4096
- Difference frame removes common structure
- Was repeated actuator-by-actuator, better control resulted
- Need to determine levels of nonlinearity
  - Quadratic
  - Hysteresis \*



## **Typical Closed Loop Results**





**Corrects low-mid spatial freq effects** 

Residuals show OAP "gouges", which are smaller than the DM actuators and are not correctable

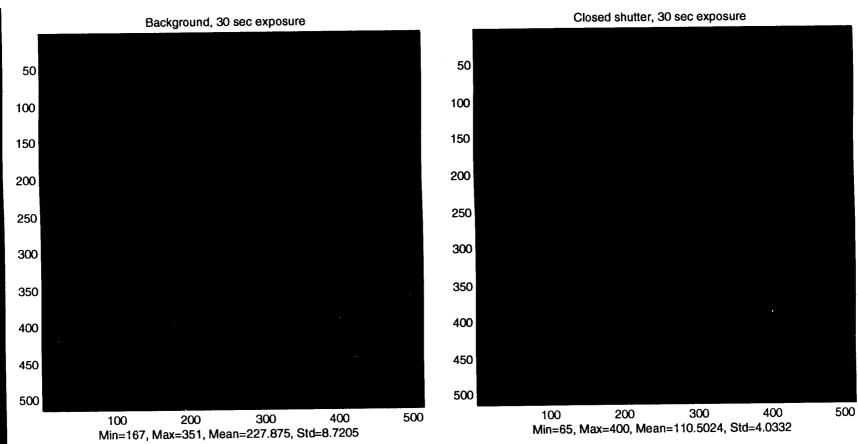
Corrected WF is consistently about  $\lambda$ /20

- DM linearity???
- DM reset between actuations may be a problem



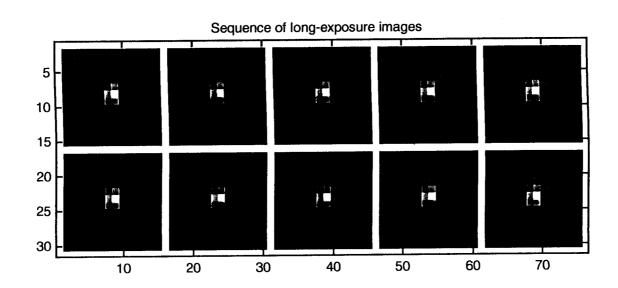
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#### **Dark Frames**



- Shutter open frame combines bias, read noise, dark current, stray light
- Shutter closed frame combines bias, read noise and dark current

## Jitter and Lab Seeing (cont.)



Long exposure images

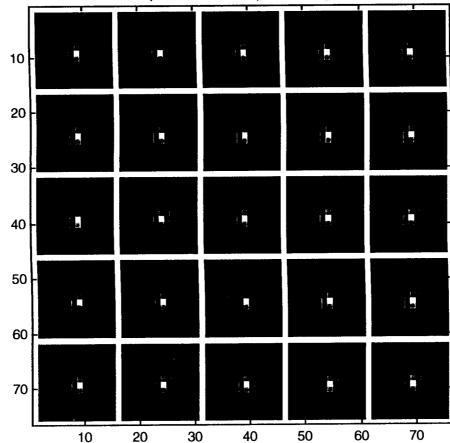
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## Jitter and Lab Seeing



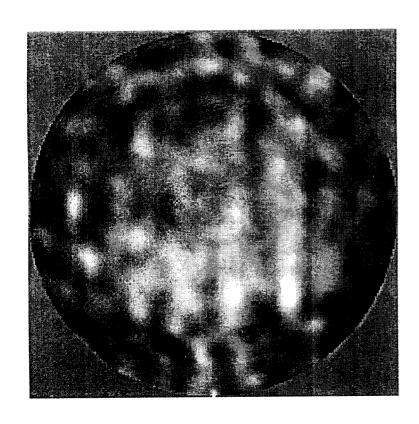


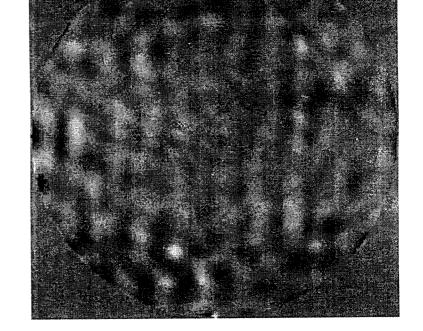
- Sequence of short-exposure images taken to show jitter
  - Lab seeing
  - Mechanical vibration
  - Shutter speed = 0.1sec

# SSAC initial flattening results

Before

After



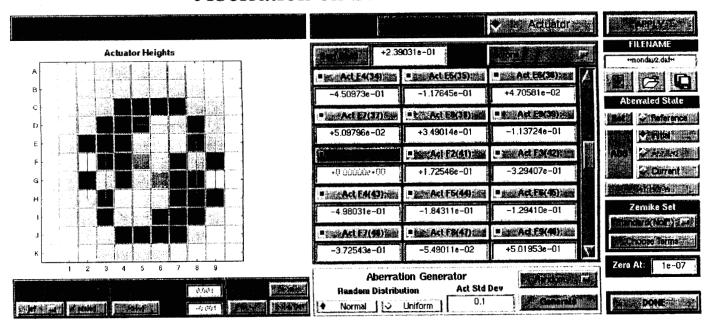


RMS wavefront = 0.06439 waves

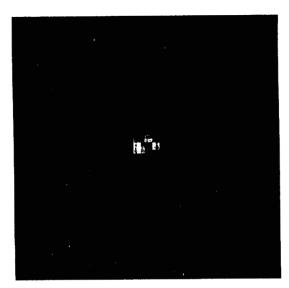
RMS wavefront = 0.03089 waves

### **Closed Loop Performance Results**

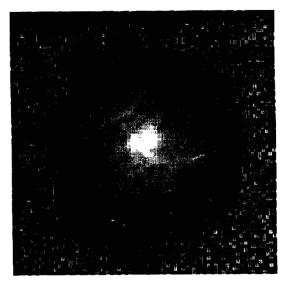
#### Aberration on Simulator DM

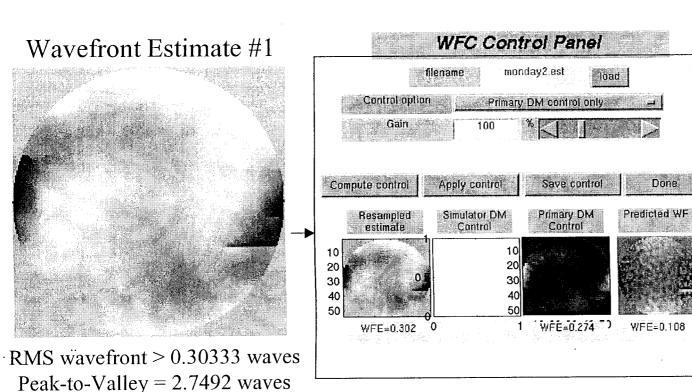


**Initial PSF** 

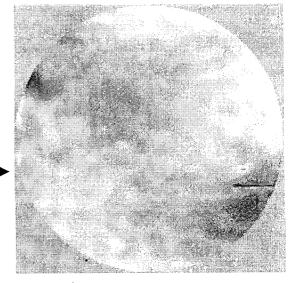


Initial PSF (log scale)



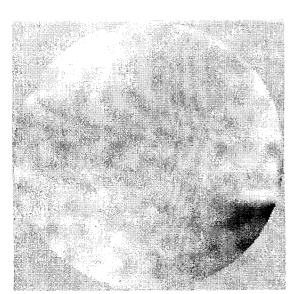


Wavefront Estimate #2



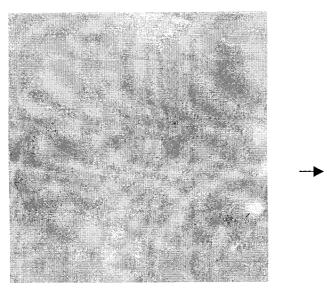
RMS wavefront = 0.25560 waves Peak-to-Valley = 2.3186 waves

#### Wavefront Estimate #3



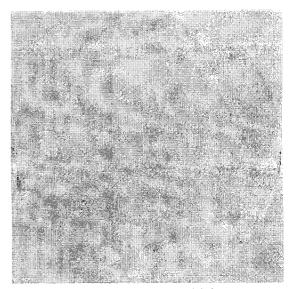
RMS wavefront = 0.16037 waves Peak-to-Valley = 1.9256 waves

#### Wavefront Estimate #4



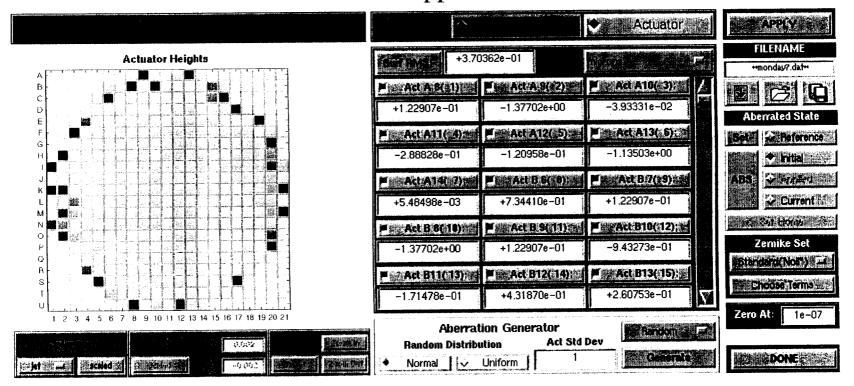
RMS wavefront = 0.07669 waves Peak-to-Valley = 0.8968 waves

#### Wavefront Estimate #5

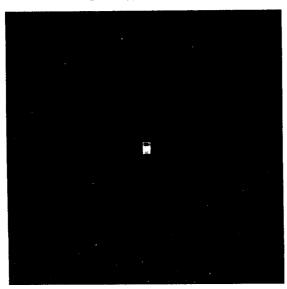


RMS wavefront = 0.04987 waves Peak-to-Valley = 0.7450 waves

#### Final correction applied to AODM



Final PSF



Final PSF (log scale)

